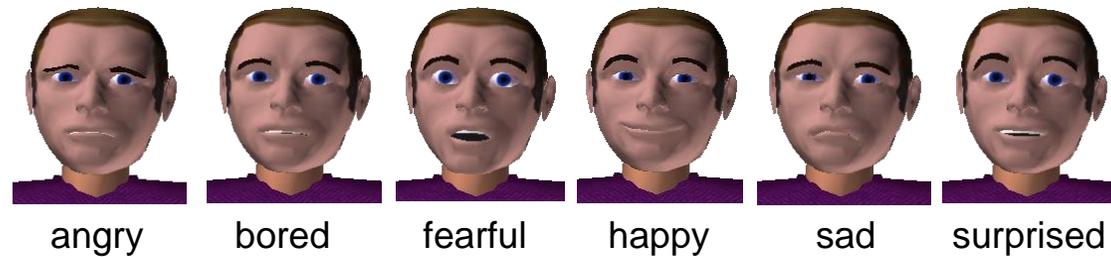




# Emotion Simulation and Android Andrea in the wild

Waseda University, 22.05.2025  
Prof. Dr. C. Becker-Asano, Hochschule der Medien, Stuttgart



# WASABI emotion simulation

WASABI Affect Simulation for Agents with Believable Interactivity

# WASABI – historical & theoretical roots

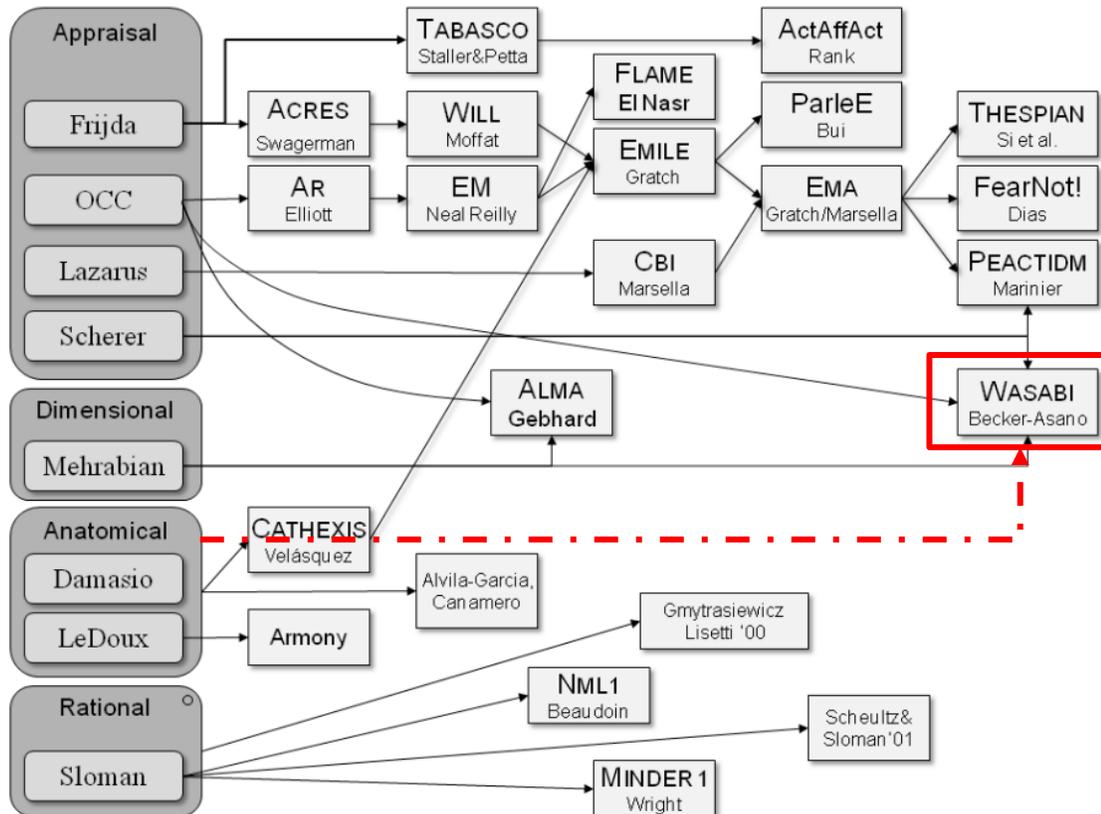


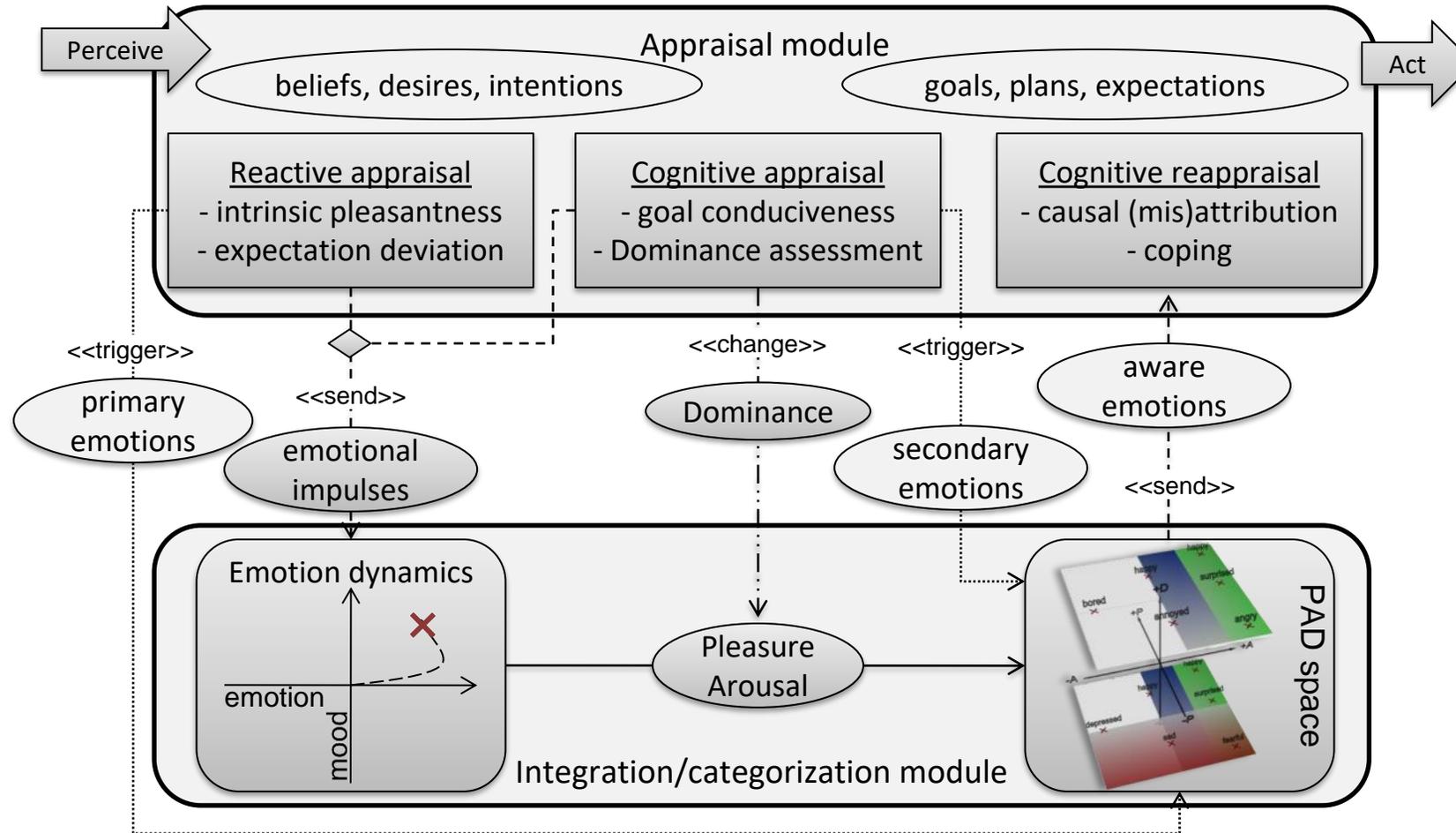
Figure 1: A history of computational models of emotion

- > Development began in 2002 with the Multimodal Assembly eXpert MAX
- > Inspired by seminal work of German philosopher and psychologist Wilhelm Wundt
- > Dynamics of emotional experience is at its core
- > Combines appraisal (OCC) with dimensional (PAD) emotion theories
- > Applied to virtual humans and social robots
- > „WASABI“ because „TABASCO“ was already taken 😊



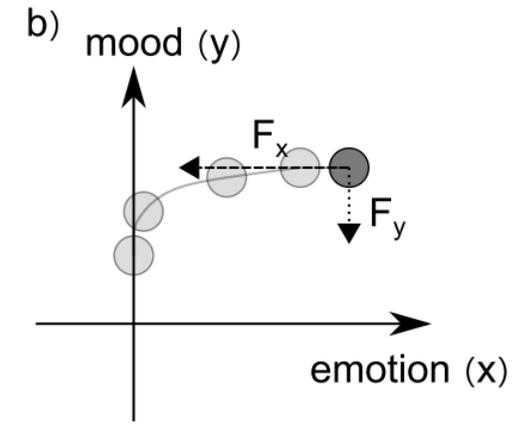
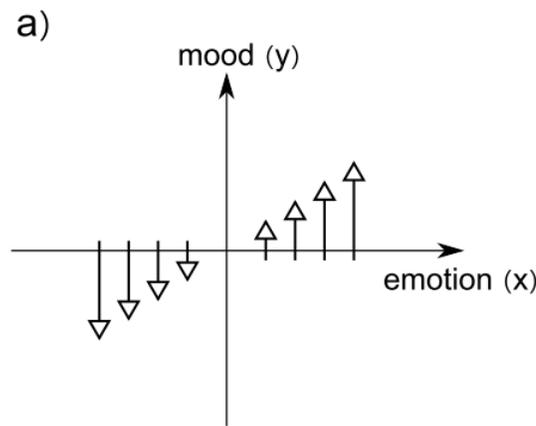
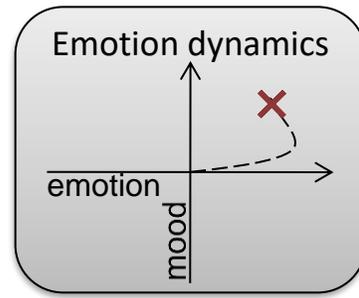
Source: Marsella, S., Gratch, J., & Petta, P. (2010). Computational models of emotion. A Blueprint for Affective Computing-A sourcebook and manual, 11(1), 21-46.

# A short introduction to WASABI



[W]ASABI [A]ffect [S]imulation for [A]gents with [B]elievable [I]nteractivity

# WASABI



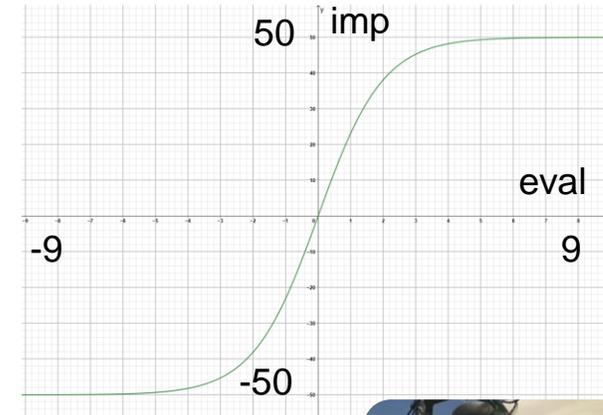
WASABI emotion dynamics:

- > emotion combined with mood
- > “valenced impulses” drive agent’s emotional state,  
for example, with a chess engine:

- > with  $e_t$  the board evaluation:

$$\text{imp}(\text{eval}_t) = k \times \tanh \frac{\text{eval}_t}{r}$$

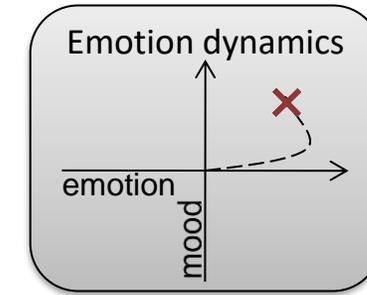
- >  $r$  reduces skewness of hyperbolic tangent (2)
- >  $k$  is a scaling factor (50)
- > E.g.,  $\text{imp}(\text{eval}_t) = 50 \times \tanh \frac{\text{eval}_t}{2}$



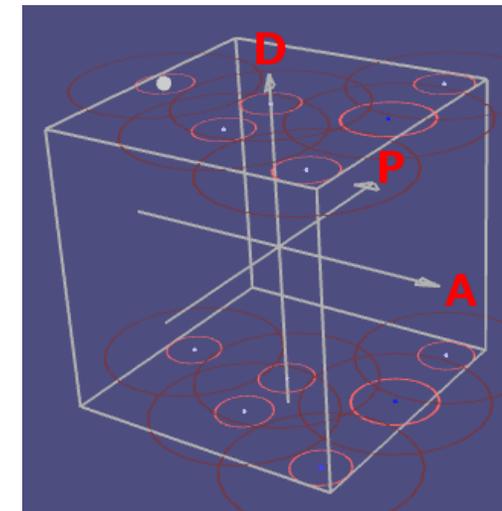
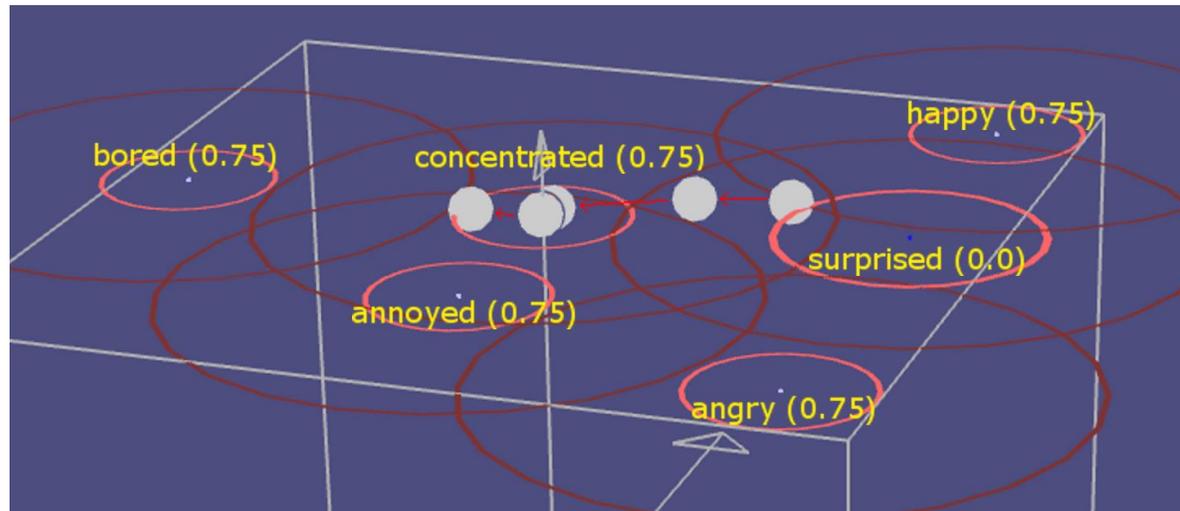
# WASABI

$$p(x_t, y_t) = \frac{1}{2} \cdot (x_t + y_t)$$

$$a(x_t, z_t) = |x_t| + z_t$$

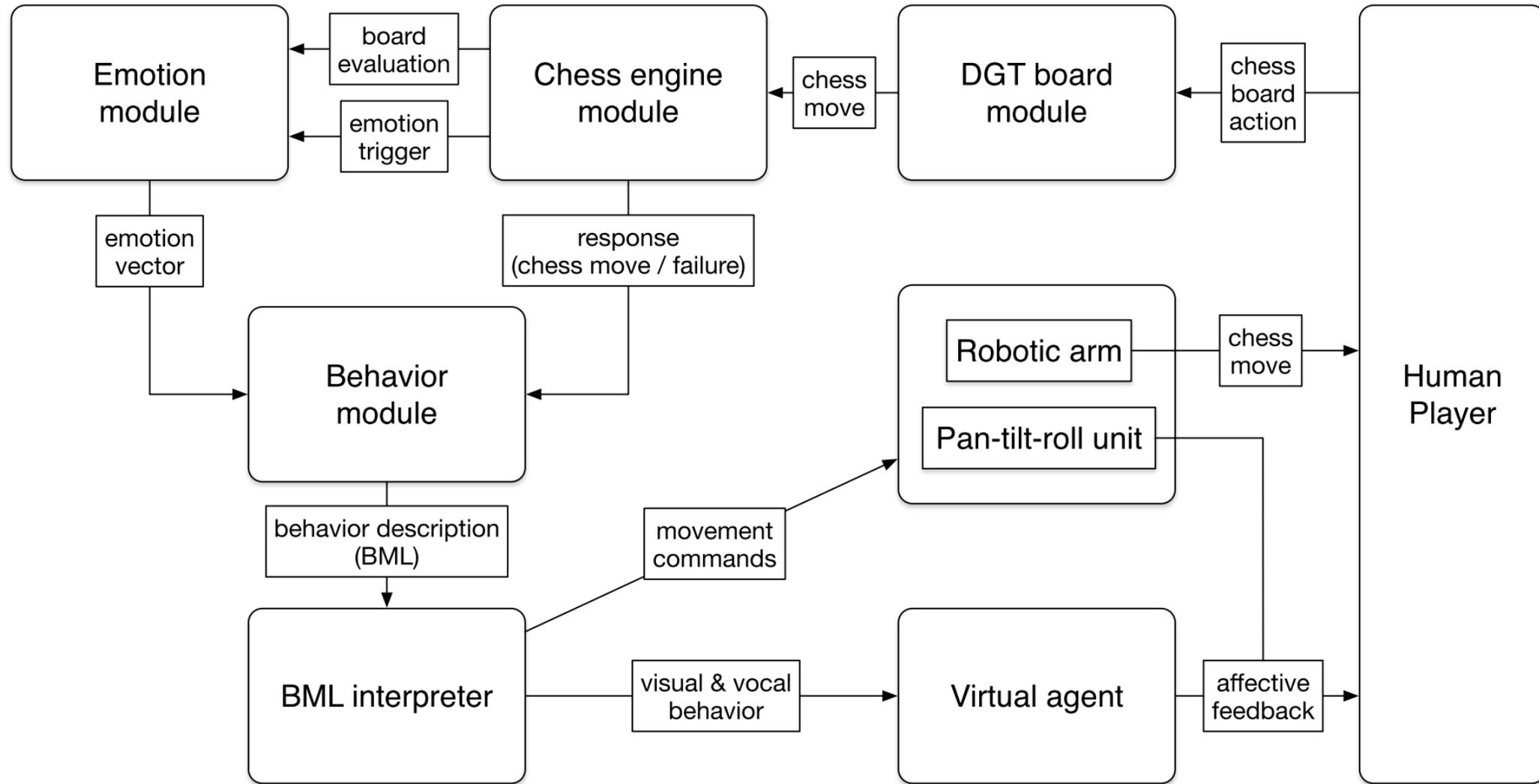


- > Emotion dynamics in pleasure (P), arousal (A), and dominance (D) space
- > Simple, UDP-based network interface
- > Open source (hosted on GitHub) (→ <https://github.com/CBA2011>)
- > (Presumably) quite well documented 😊



# Software architecture of MARCO

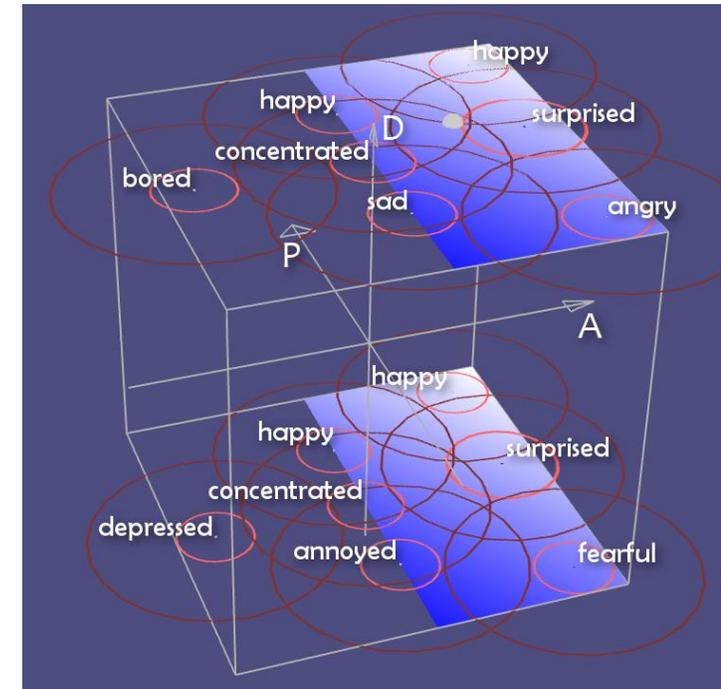
2014



# WASABI integration (2)

2014

- > prospect-based emotions need to be triggered based on changing evaluations over time
- > with  $e_t$  representing future directed evaluation:
  - > fear: significant drop of board evaluation
  - > surprise: significant change of board evaluation
  - > fear-confirmed: if fear is present and situation as bad as expected (or even worse)
  - > relief: if fear and situation much better than expected
  - > hope: if good move at depth  $d$  of the search tree



<i>trigger</i>	<i>if..</i>
fear	$e_{t-1} - e_t > \epsilon$
surprise	$ e_{t-1} - e_t  > \epsilon$
fears-confirmed	$fear_{t-1} \wedge (e_{t-1} - e_t < \epsilon)$
hope	$e_{t,d} - e_{t,d-2} > \epsilon$
relief	$fear_{t-1} \wedge (e_t - e_{t-2} < \epsilon)$



2014

# MARCO: Multimodal Autonomous-Robotic Chess Opponent

Demo at ICFI 2014

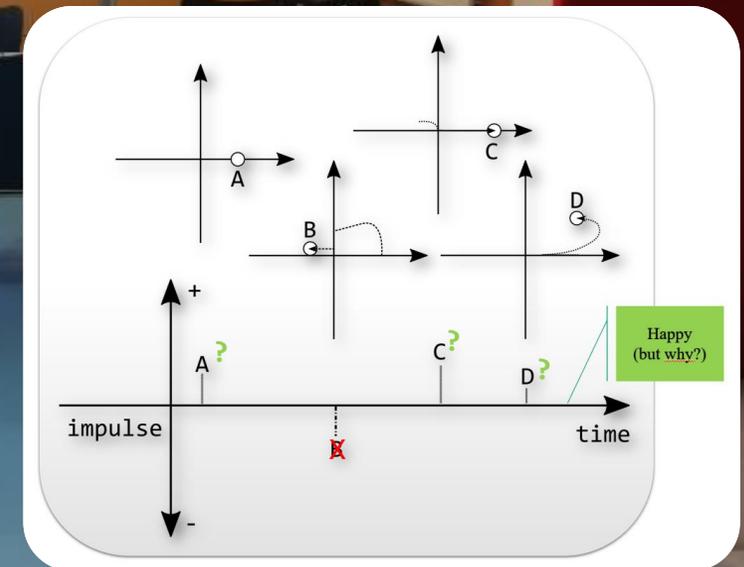
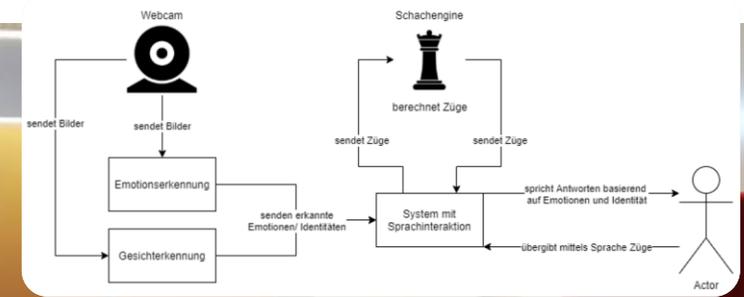
November 13, Istanbul, Turkey  
(Outstanding Demo Award)

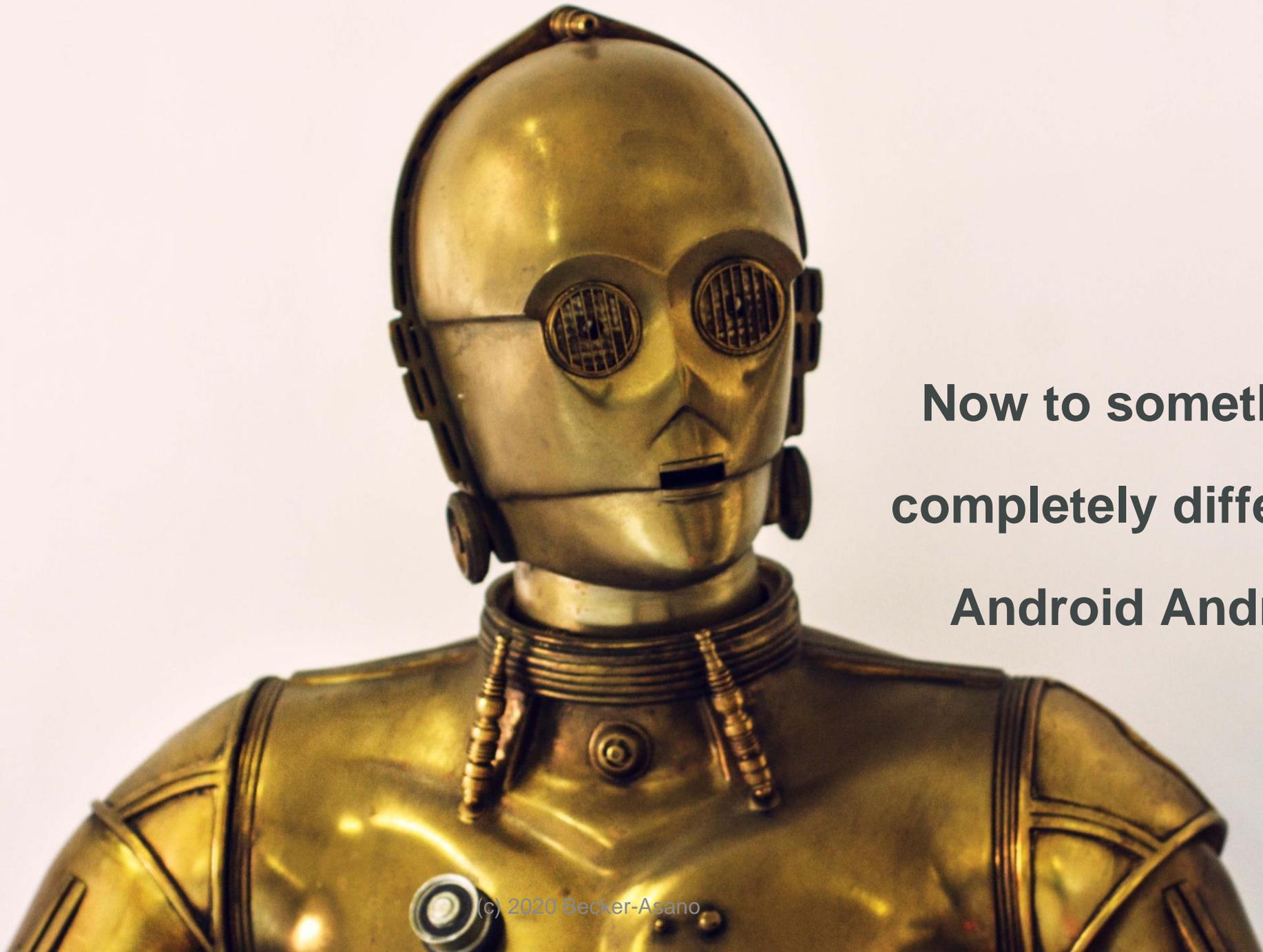
**Outstanding demo award  
ICMI 2014, Istanbul**

<https://becker-asano.de/index.php/videos/robotics/87-marco-videos>

# MARCO Bachelor & master thesis @ humanoidlab

- > 2021, Sinan Kale, MA: „Development and integration of an **optical chess board recognition from an oblique angle** for the hybrid agent MARCO“
- > 2021, Jannik Schmidt, BA: „Personalized spoken language interaction with a chess robot by **camera-based face and emotion recognition**“
- > 2022, Florian Rapp, BA: „**Emotion detection from the speech signal**“
- > 2022, Patrick Thomasius, BA: „**Misattribution of emotions** – analysis and simulation following an emotion dynamics approach“
- > ...





**Now to something  
completely different:  
Android Andrea**

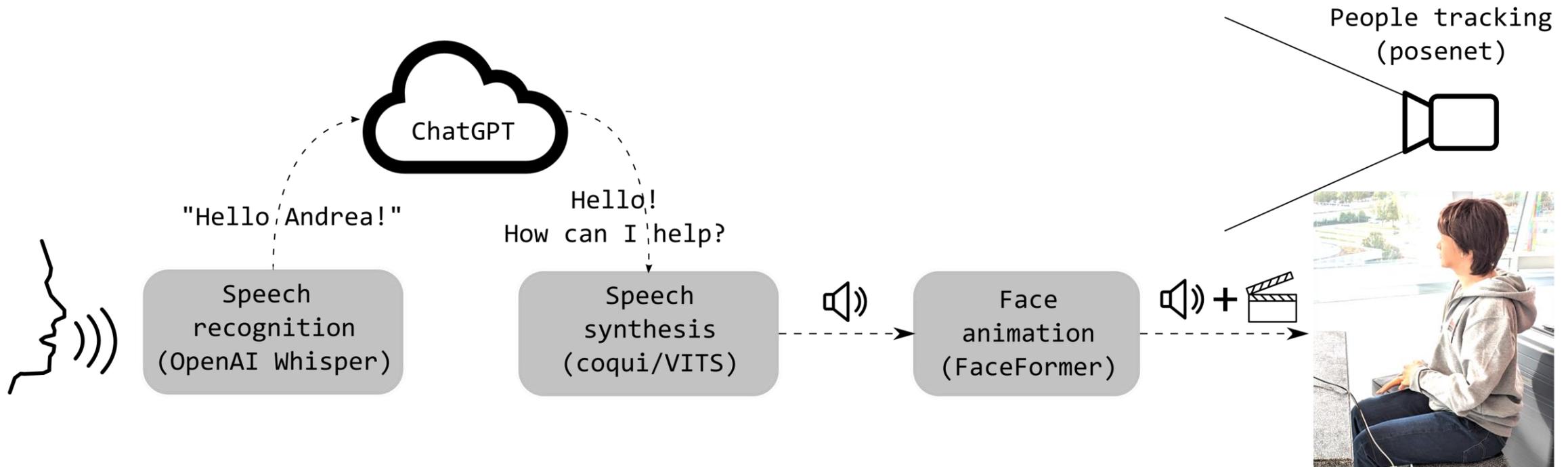
# Impression of the setup



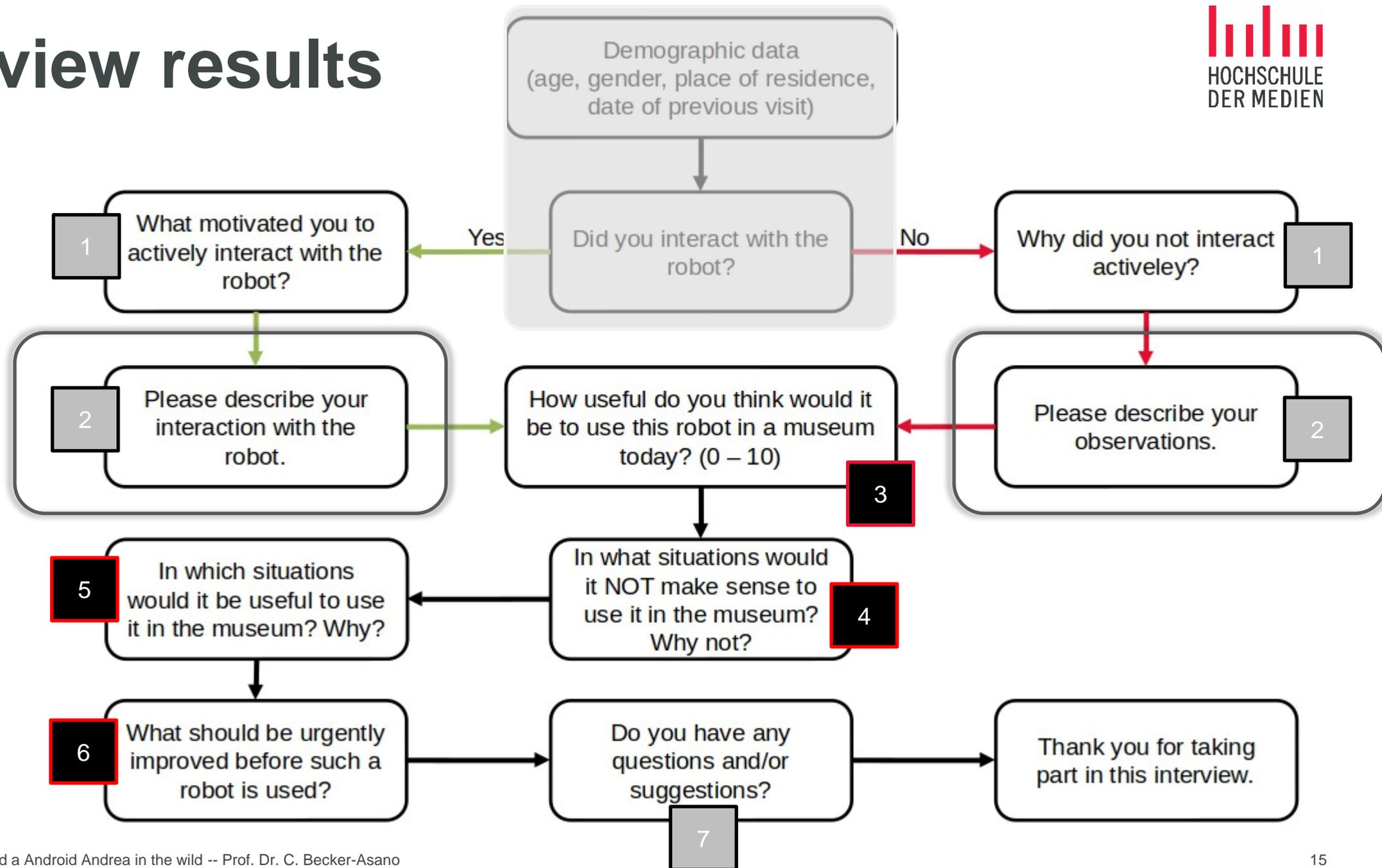
# Project overview

- › Interactive installation of the android robot “Andrea” in the “Galerie der Reisen” of the Mercedes-Benz museum
- › Daily from 9 am to 6 pm, October 31<sup>st</sup> until November 5<sup>th</sup> 2023
- › Structured interviews with 44 randomly selected visitors
- › Three versions of Andrea:
  1. Long hair with female voice (long-female, 2 days)
  2. Short hair with male voice (short-male, 3 days)
  3. Short hair with female voice (short-female, 1 day)
- › Analysis of 44 interviews and 4436 audio input requests (transcribed to text) with corresponding system responses

# Technical setup



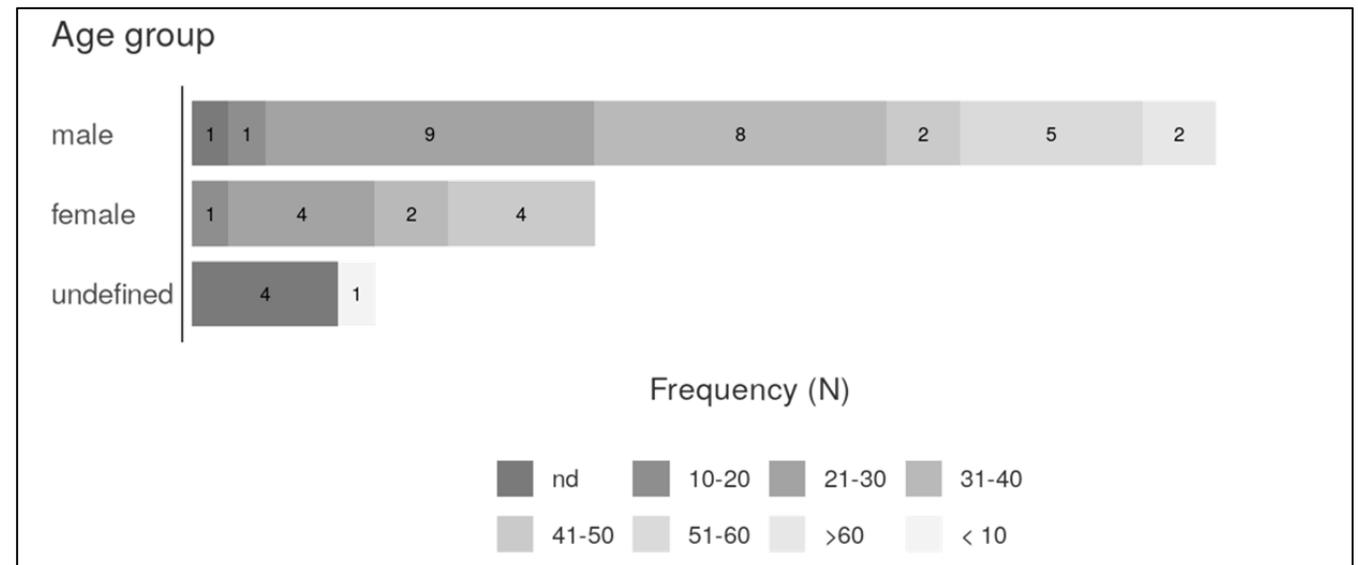
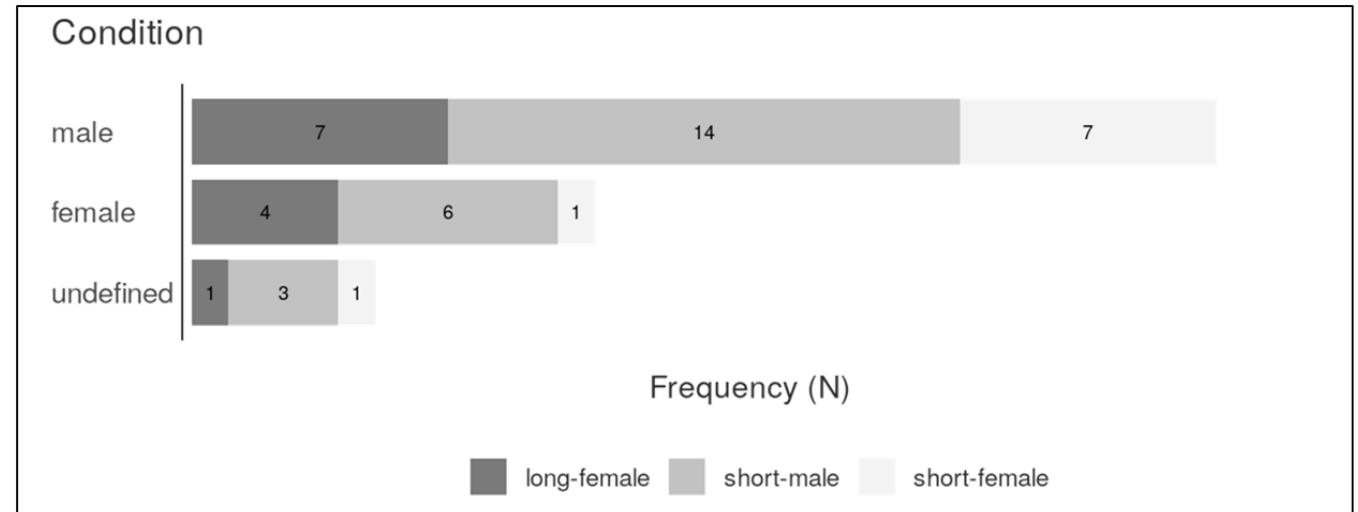
# Interview results



# Gender over conditions / age groups

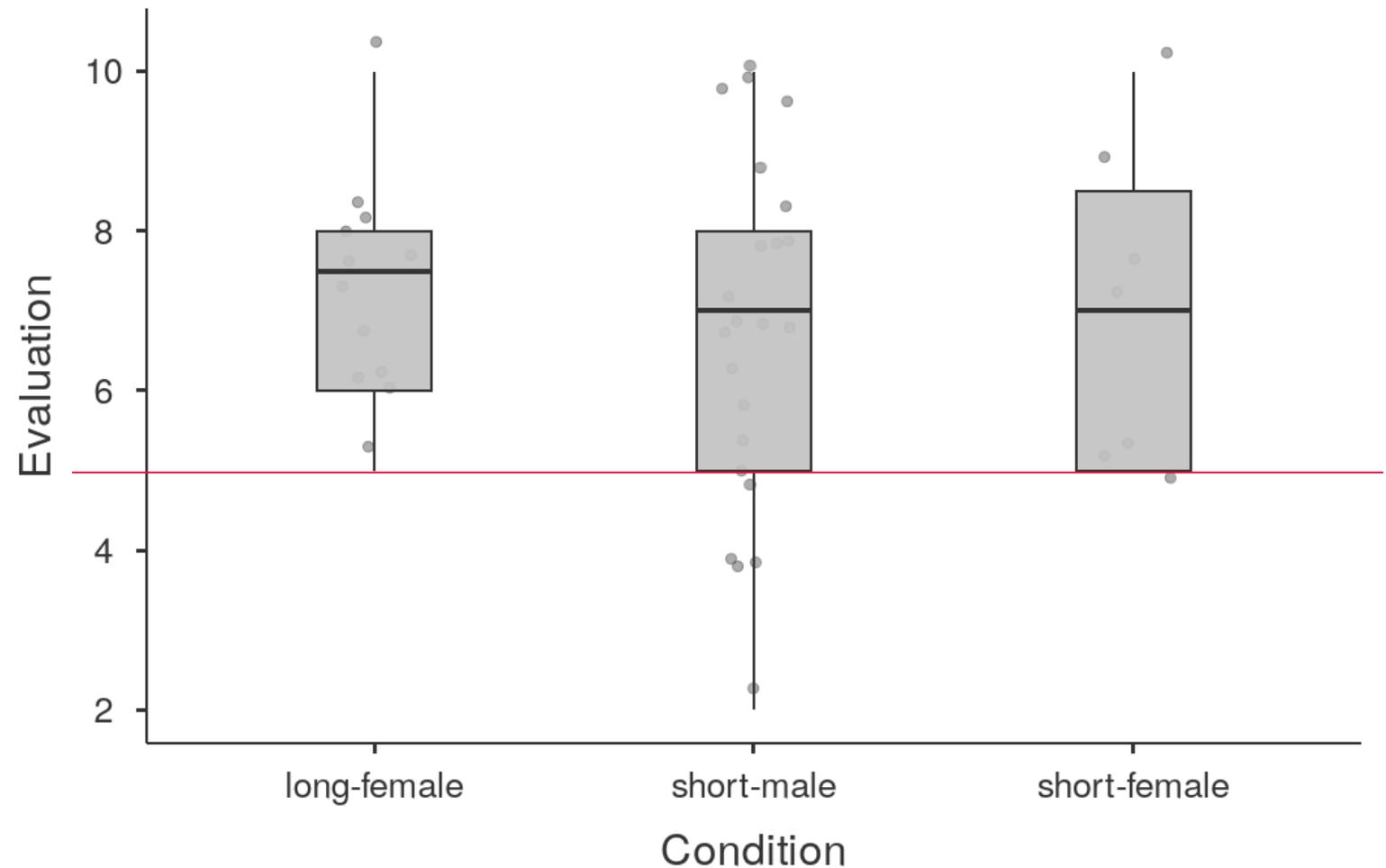
Demographic data  
(age, gender, place of residence,  
date of previous visit)

- > 28 male, 11 female, 5 undefined (missing data)
- > Equal distribution of gender over experimental conditions
- > Equal distribution of gender over age groups



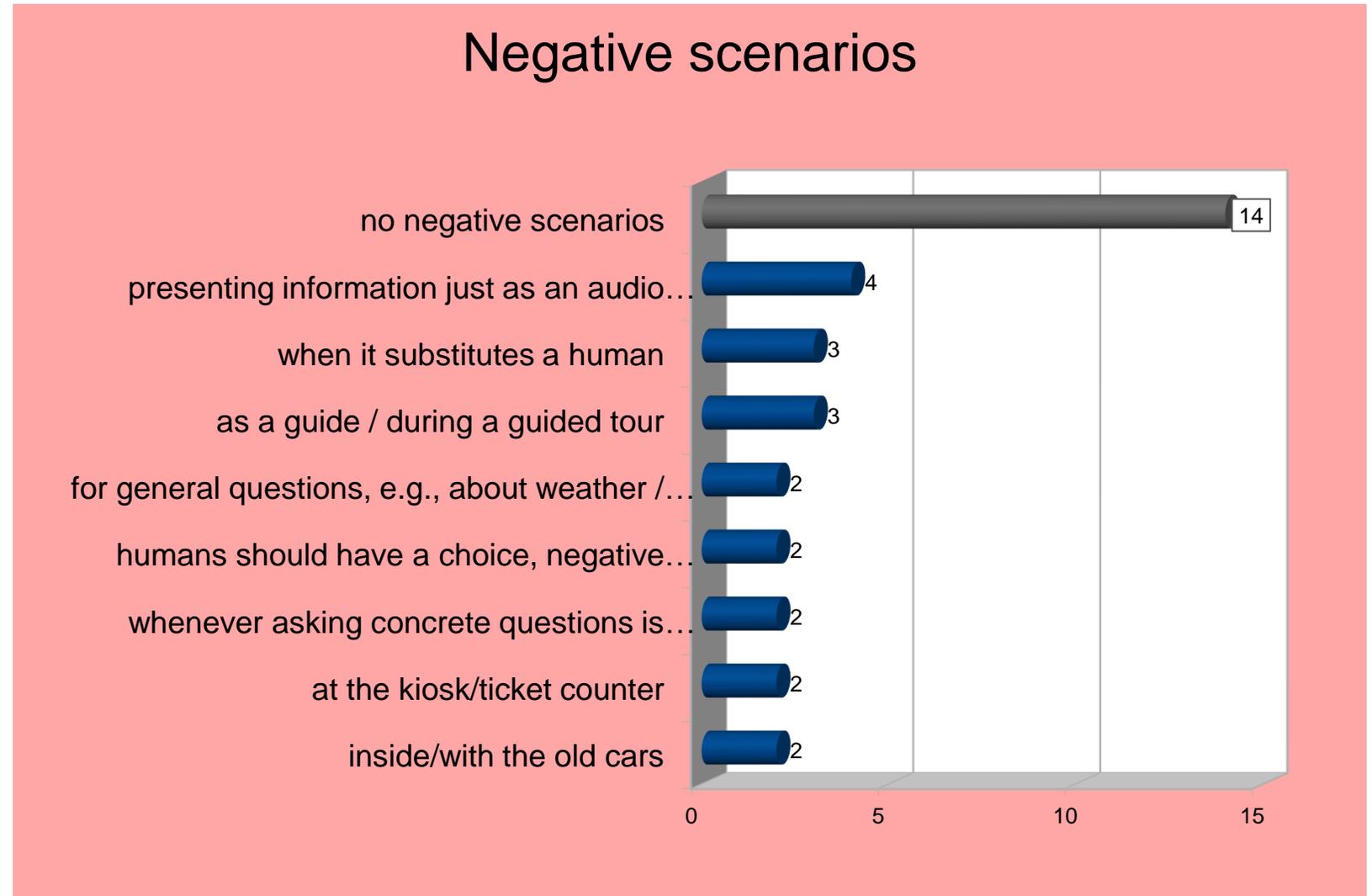
# Usefulness on a 0 to 10 scale

- > All conditions well above average evaluation of five
  - > pooled evaluation data:  
Shapiro-Wilk normality test  $p = 0.056 \rightarrow$  Wilcoxon test with  $H_0 \mu \neq 5, p < 0.001$
- > No significant differences between conditions
  - > One-way ANOVA assuming unequal variances with „Condition“ as grouping variable:  $F = 0.237, df_1 = 2, df_2 = 15.9, p > 0.79$



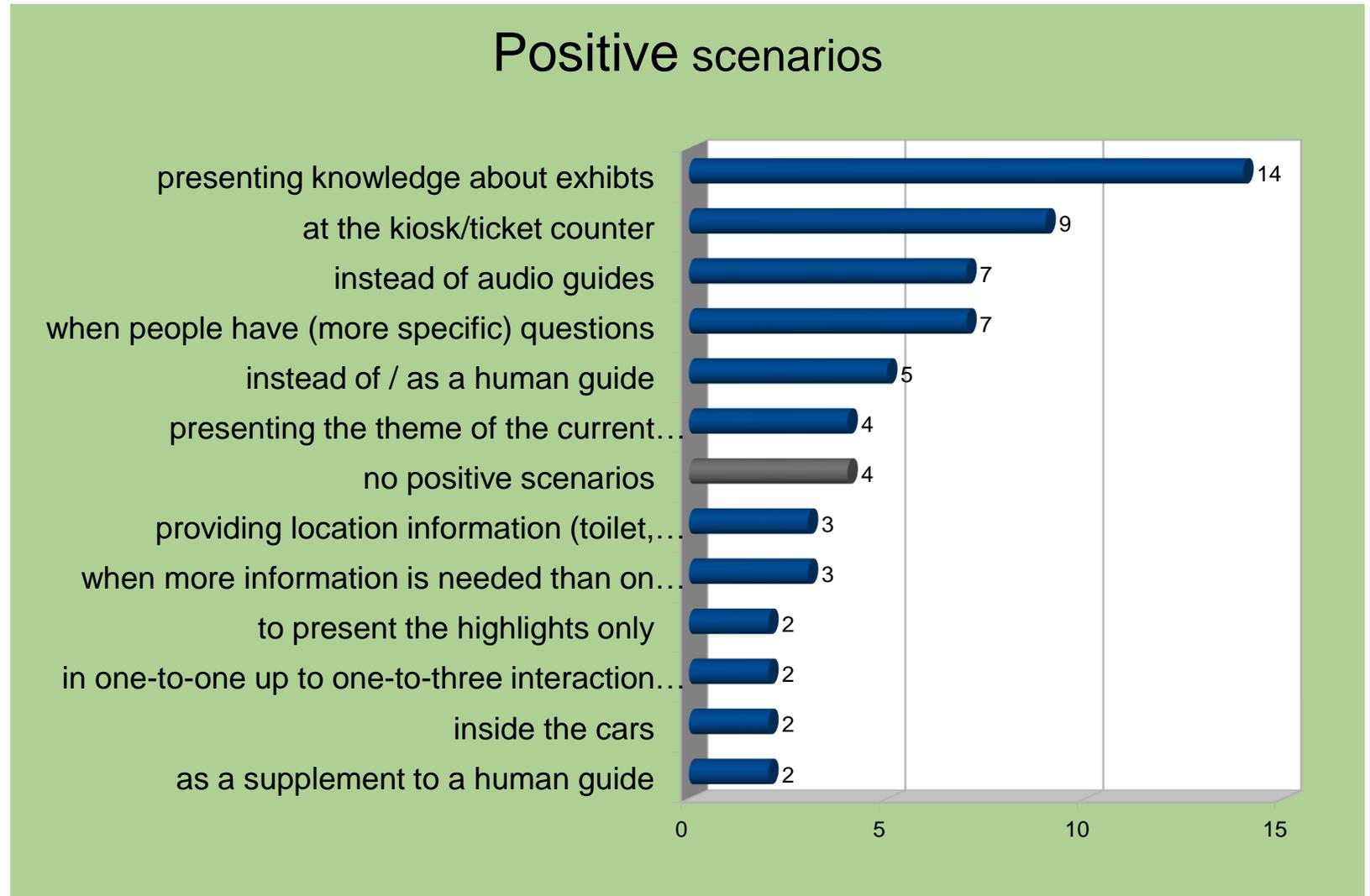
# Scenarios that are not making sense

- > Many visitors did not come up with any negative scenarios
- > Some do not want Andrea instead of an audio guide

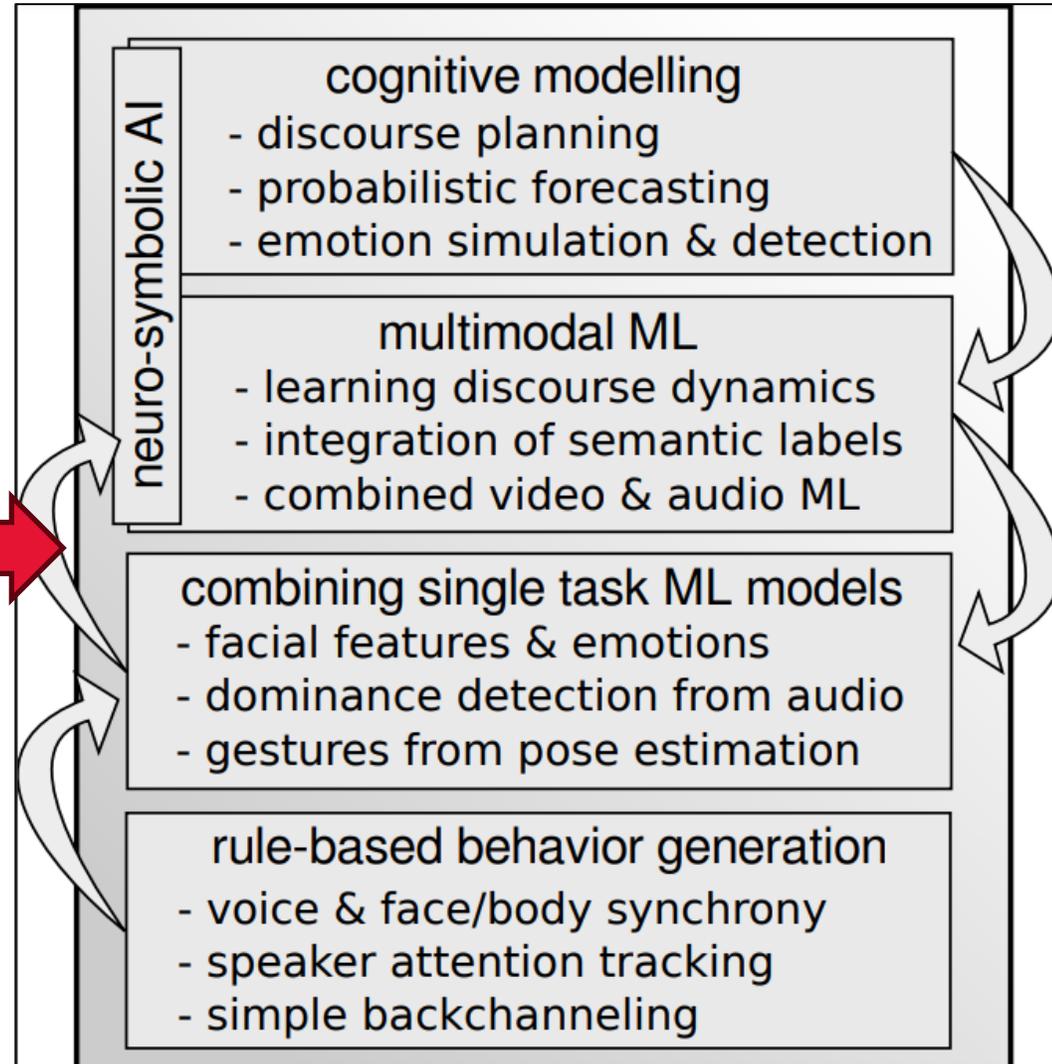
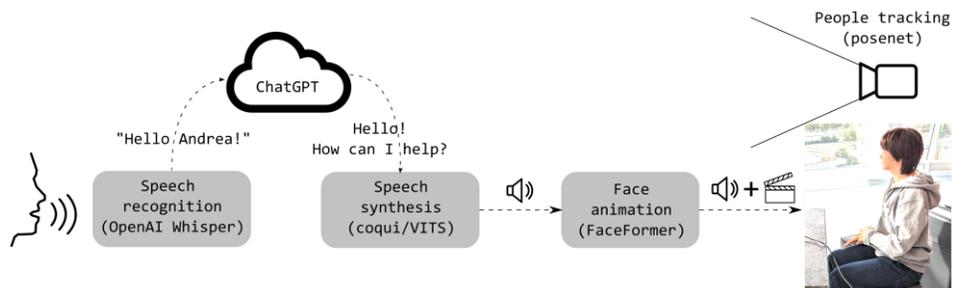


# Scenarios that are making sense

- > Nearly every third visitor wants to let Andrea present exhibits
- > Nine can imagine to let Andrea work at the ticket counter
- > Even as a replacement of audio guides is possible for some visitors



# What's next?



# Cooperation with Japan – ERICA / ATR



# Humanoid Lab at Stuttgart Media University



Marcel Heisler  
Stuttgart Media University  
ML, software framework, facial  
animation



Johanna Kuch  
University of Augsburg  
Speech & Gender neutral design



Leon Kiefer  
Stuttgart Media University  
ML, Vision, Object recognition

